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# **METHOD OF CALCULATING NOISE FROM MULTIPLE DIGITAL IMAGES UTILIZING COMMON NOISE CHARACTERISTICS**

## **FIELD OF INVENTION**

The present invention relates to a method for enhancing digital  
5 images using a noise characteristic common to such noise characteristics.

## **BACKGROUND OF THE INVENTION**

Some digital image processing applications designed to enhance  
the appearance of the processed digital images take explicit advantage of the noise  
characteristics associated with the source digital images. For example, Keyes et  
10 al. in U.S. Patent 6,118,906 describe a method of sharpening digital images which  
includes the steps of measuring the noise components in the digital image with a  
noise estimation system to generate noise estimates and sharpening the digital  
image with an image sharpening system which uses the noise estimates.  
Similarly, digital imaging applications have incorporated automatic noise  
15 estimation methods for the purpose of reducing the noise in the processed digital  
images as in the method described by Anderson et al. in U.S. Patent 5,809,178.

In U.S. Patent 5,923,775, Snyder et al. disclose a method of image  
processing which includes a step of estimating the noise characteristics of a digital  
image and using the estimates of the noise characteristics in conjunction with a  
20 noise removal system to reduce the amount of noise in the digital image. The  
method described by Snyder et al. is designed to work for individual digital  
images and includes a multiple step process for the noise characteristics estimation  
procedure. First, the residual signal is formed from the digital image obtained by  
applying a spatial filter to the digital image. This first residual is analyzed to form  
25 a mask signal which determines what regions of the digital image are more and  
less likely to contain image structure content. The last step includes forming a  
second residual signal and sampling the residual in image regions unlikely to  
contain image structure content to form the noise characteristic estimation.

In U.S. Patent 6,069,982, Reuman describes a method of estimating  
30 the noise characteristics of a digital image acquisition device which includes

providing predetermined default values for the spatial noise characteristics of the digital image acquisition device, gathering information related to the spatial noise characteristics of the digital image acquisition device; generating replacement data in response to the gathered information; and updating the predetermined default spatial noise characteristics associated with the digital image acquisition device with the replacement data. In particular the method disclosed by Reuman estimates the standard deviation (derived from the variance) as a function of the grey-level (pixel value) and the spatial frequency characteristics of the noise. The noise characteristics, such as a table of standard deviation values as a function of grey-level, are provided as the default values. Each digital image to be processed is analyzed which includes the calculation of statistical quantities in the gathering of information step. These statistical quantities and the default values are combined to calculate the updated replacement noise characteristic values. Furthermore, in the method taught by Reuman, a yes/no decision is made with regard to the presence or the lack of the default noise values. If the default noise values are present, they are used. If the default noise values are not present, they are generated from the digital image to be processed with the aid of the operator of the system.

In the method taught by Reuman, the estimated noise characteristic values are specific to a digital image acquisition device. Reuman gives examples of digital images acquisition devices such as a film scanner, digital camera, or an image processing module. Although film scanners can add noise to the digital images they produce, much of the noise present in the output digital images can be attributed to the photographic film type. Thus, the noise characteristic values associated with the digital images derived from a scanned photographic film can be attributed to the type of photographic film independent of the film scanner device used to produce the digital image.

In U.S. Patent 5,959,720 Kwon et al. disclose a method of color balance determination for use by a color copying apparatus utilizing multiple image frames of a photographic film order. Multiple individual digital images are

produced by a film scanner and the pixel data of these digital images is collectively analyzed to calculation a color balance point relating to the set of digital images. The color balance point is then used to process each digital image for improved color balance. The method disclosed by Kwon et al. is an example  
5 of a digital imaging analysis method which combines the analysis of pixel data from multiple digital images to improve the processing of pixel data for each of the digital images.

### SUMMARY OF THE INVENTION

It is an object of the present invention to provide an improved way  
10 of enhancing digital images, which are believed to be affected by a common noise source.

This object is achieved by a method of enhancing one or more digital images from a plurality of digital images that are believed to be affected by a common noise source, comprising the steps of:

- 15 a) receiving two or more source digital images that are believed to be affected by a common noise source;
- b) using the pixels of the received source digital images to calculate a noise characteristic value that relates to the noise present in the received source digital images; and
- 20 c) using the noise characteristic value and the received source digital images to respectively calculate enhanced digital images for the one or more of the received source digital images.

It is a feature of the present invention to provide for improved image enhancement by taking advantage of the fact that for a particular group of  
25 digital images, they will contain similar amounts of noise. The present invention is particularly advantageous for enhancing images which are taken on a common photographic film type. These images will all share common noise characteristics which are substantially contributed to by the photographic film. Nevertheless, the present invention also is useful when the digital images are provided by a scanner  
30 or digital camera which also introduces common noise.

## BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a functional block diagram showing the component parts of a digital imaging system implementation of the present invention;

FIG. 2 is a functional block diagram of the digital image processor module shown in FIG. 1 employed by a preferred embodiment of the present invention;

FIG. 3 is a function block diagram of the noise estimation module shown in FIG. 2 used by the preferred embodiment of the present invention;

FIG. 4 is a function block diagram of the noise estimation module used by an alternative embodiment of the present invention; and

FIG. 5 is a function block diagram of the noise estimation module used by another alternative embodiment of the present invention.

## DETAILED DESCRIPTION OF THE INVENTION

In the following description, a preferred embodiment of the present invention will be described as a software program. Those skilled in the art will readily recognize that the equivalent of such software may also be constructed in hardware. Because image manipulation algorithms and systems are well known, the present disclosure will be directed in particular to algorithms and systems forming part of, or cooperating more directly with, the method in accordance with the present invention. Other aspects of such algorithms and systems, and hardware and/or software for producing and otherwise processing the image signals involved therewith, not specifically shown or described herein may be selected from such systems, algorithms, components, and elements known in the art. Given the description as set forth in the following specification, all software implementation thereof is conventional and within the ordinary skill in such arts.

The present invention may be implemented in computer hardware. Referring to FIG. 1, the following description relates to a digital imaging system which includes an image capture device 10a, a digital image processor 20, an image output device 30a, and a general control computer 40. The system may include a monitor device 50 such as a computer console or paper printer. The

system may also include an input device control 60 for an operator, such as a keyboard and or mouse pointer. Multiple capture devices 10a, 10b, and 10c are shown illustrating that the present invention may be used for digital images derived from a variety of imaging devices. For example, FIG. 1 may represent a digital photofinishing system where the image capture device 10a is a conventional photographic film camera for capturing a scene on color negative or reversal film, and a photographic film scanner for scanning the developed image on the film and producing a digital image. Although the term scanner can refer to digital imaging devices that physically scan or move a sensing element past a photographic film sample, the present invention also includes photographic film scanners and print scanners that employ a stationary image sensing device to generate a digital image. The digital image processor 20 receives a set of digital images, processes these digital images to produce an enhanced digital image for one or more digital image in preparation for the intended output device or media. The digital image processor 20 analyzes the noise characteristics of the set of digital images and modifies the spatial characteristics of these digital images by employing a noise reduction filter and a spatial sharpening filter. In addition, the digital image processor 20 may process the set of digital images to make adjustments for color, density and tone scale in a manner such that a pleasing looking image is produced by an image output device 30a. Those skilled in the art will recognize that the present invention is not limited to just these mentioned image processing modules. Multiple image output devices 30a and 30b are shown illustrating that the present invention may be used in conjunction with a variety of output devices which may include a digital photographic printer and soft copy display. The present invention uses a digital photographic printer to make a print of the enhanced digital images to make photographic prints.

The general control computer 40 shown in FIG. 1 may store the present invention as a computer program stored in a computer readable storage medium, which may comprise, for example: magnetic storage media such as a magnetic disk (such as a floppy disk) or magnetic tape; optical storage media such

as an optical disc, optical tape, or machine readable bar code; solid state electronic storage devices such as random access memory (RAM), or read only memory (ROM). The associated computer program implementation of the present invention may also be stored on any other physical device or medium employed to  
5 store a computer program indicated by offline memory device 70. Before describing the present invention, it facilitates understanding to note that the present invention is preferably utilized on any well known computer system, such as a personal computer.

It should also be noted that the present invention implemented in a  
10 combination of software and/or hardware is not limited to devices which are physically connected and/or located within the same physical location. One or more of the devices illustrated in FIG. 1 may be located remotely and may be connected via a wireless connection.

A digital image is comprised of one or more digital image  
15 channels. Each digital image channel is comprised of a two-dimensional array of pixels. Each pixel value relates to the amount of light received by a image capture device corresponding to the geometrical domain of the pixel. For color imaging applications a digital image will typically consist of red, green, and blue digital image channels. Other configurations are also practiced, e.g. cyan, magenta, and  
20 yellow digital image channels. For monochrome applications, the digital image consists of one digital image channel. Motion imaging applications can be thought of as a time sequence of digital images. Those skilled in the art will recognize that the present invention can be applied to, but is not limited to, a digital image channel for any of the above mentioned applications. Although the  
25 present invention describes a digital image channel as a two dimensional array of pixel values arranged by rows and columns, those skilled in the art will recognize that the present invention can be applied to mosaic (non rectilinear) arrays with equal effect.

While the discussion of the present invention hereinbelow  
30 describes processing digital images, it should be noted that processing digital

images does not necessarily require that the entirety of a digital image must be processed. For example, selected regions within a digital image can be processed without processing the entire digital image and the digital image can still be said to have been processed. Similarly, the present invention can be practiced by  
5 processing only some of the digital image channels included in a digital image. It should also be noted that the present invention can be practiced with digital images of a variety of different image representations. For example, the present invention can be practiced with digital images having color pixels of red, green and blue. However, the present invention can also be practiced with digital  
10 images in a luminance-chrominance image representation.

The digital image processor 20 shown in FIG. 1 is illustrated in more detail in FIG. 2. The general form of the digital image processor 20 employed by the present invention is a cascaded chain of image processing modules. The noise estimation module 110 receives the source digital images 101 and calculates a local noise characteristic table 105, i.e. a table of noise  
15 characteristic values, using the pixel values from the source digital images 101. Each image processing module contained within the digital image processor 20 receives a digital image, modifies the digital image, produces a processed digital image and passes the processed digital image to the next image processing  
20 module. The two enhancement transform modules shown within the digital image processor 20 are a noise reduction module 22 and a spatial sharpening module 23. These two modules use the local noise characteristic table 105 produced by the noise estimation module 110 to generate the enhanced digital images 102. Those skilled in the art will recognize that the any other image processing module that  
25 utilizes a noise characteristic table can be used with the present invention.

The noise estimation module 110 shown in FIG. 2 is illustrated in more detail in FIG. 3. The source digital images 101 are received by the digital image indexer 115 which dispatches each source digital image 101 to the residual transform module 120 for processing. The residual transform module 120  
30 receives a source digital image 101, performs a spatial filtering operation on the



pixel data of the source digital image 101 resulting in a residual digital image.

The residual digital image produced for each source digital image 101 is received by the residual statistical accumulator 130 which calculates a set of local residual histograms. When the digital image indexer 115 has dispatched all of the source digital images 101, the digital image indexer 115 sends a message to the noise  
5 table calculator 140 that all of the source digital images 101 have been processed. The noise table calculator 140 receives the set of local residual histograms and produces a local noise characteristic table 105.

The residual transform module 120 uses a residual spatial filter to  
10 perform a spatial filtering operation on the pixel data of a digital image. A residual pixel value is generated for each original pixel value in the source digital image 101 by the residual spatial filter. For each pixel of interest, a combination of pixel values sampled from a local region of pixels is used to form the residual pixel value. If the source digital image 101 is a color digital image, the residual  
15 transform module 120 performs the spatial filtering operation on each color digital image channel and forms a residual pixel value for each pixel of each color digital image channel. The preferred embodiment of the present invention uses a two-dimensional Laplacian operator as the spatial filter to form the residual pixel values. The Laplacian operator calculates a local arithmetic mean value from the  
20 value of pixel sampled from the local region of pixels about the pixel of interest and subtracts the value of the pixel of interest from the local arithmetic mean value. A local region of 3 by 3 pixels is used. The Laplacian operator is a convolution spatial filter with an associated convolution kernel of:

$$\begin{array}{ccc} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & 1 \end{array} \quad (1)$$

Although the preferred embodiment of the present invention uses a two  
30 dimensional Laplacian based residual spatial filter, those skilled in the art will

recognize that the present invention can be practiced with other spatial filters, such as but not limited to, one-dimensional Laplacian spatial filters.

An alternative embodiment of the present invention uses the method disclosed by Snyder et al. in U.S. Patent 5,923,775. In this alternative  
 5 embodiment, a similar technique of forming a residual pixel value is performed. Next, a gradient signal is calculated using a spatial filter. The gradient signal is analyzed forming a masking signal that is used to reject some of the residual pixel values from later consideration. Although this alternative embodiment leads to more accurate noise estimation it is also more computationally intensive than the  
 10 preferred embodiment.

The pixel data of the source digital image 101 can be conceptualized as having two components - a signal component relating to photographed objects and a noise component. The resulting residual pixel values have statistical properties that have a closer relationship to the noise component of  
 15 the pixel data of the source digital image 101 than the signal component. Although the noise component can contain sub-components, the stochastic sub-component of the noise component is well modeled by a zero mean Gaussian probability distribution function. To first order, the noise component of the pixel data of the source digital image 101 can be characterized by a standard deviation and a mean value of zero. To second order, standard deviation of the noise  
 20 component can be modeled as being signal and color channel dependent.

The residual transform module 120 analyzes the residual pixel values and records these values in the form of a set of local residual histograms as a function of the pixel color and numerical pixel value. Therefore, a given local  
 25 residual histogram  $H_{ik}$  relates to the  $i^{\text{th}}$  color digital image channel and the  $k^{\text{th}}$  pixel value sub-range. For each pixel of interest denoted by  $p_{mn}$  (corresponding to the  $m^{\text{th}}$  row and  $n^{\text{th}}$  column location) in the processed color digital image channel, a histogram bin index  $k$  is computed. For example, if the numerical range of pixel values is from 0 to 255 there can be as many as 256 useful histograms, i.e. one  
 30 histogram for each possible numerical pixel value. In general, most noise sources

can be characterized as having noise standard deviations that are slow functions of the pixel value. Therefore, the preferred embodiment of the present invention uses 8 histograms to cover the numerical pixel value range from 0 to 255. Thus, the calculated histogram index bin and the corresponding sub-range pixel values are  
 5 given by the following Table 1.

Table 1

histogram bin index	sub-range pixel values	average pixel value
0	0 to 31	16
1	32 to 63	48
2	64 to 95	80
3	96 to 127	112
4	128 to 159	144
5	160 to 191	176
6	192 to 233	208
7	234 to 255	240

10 Those skilled in the art will recognize that the present invention can be practiced with digital image pixel data with any numerical range. The number of local residual histograms used for each color digital image channel will depend on the accuracy of results required for the particular digital imaging application.

Although each local residual histogram records statistical  
 15 information for a range of pixel values for a given color digital image channel, the local residual histogram records the frequency of residual pixel values associated with each pixel of interest  $p_{nm}$ . Since the expected mean of the distribution of residual pixel values is zero, the residual pixel values exhibit both positive and negative values. Therefore, the local residual histogram must record the  
 20 frequency, i.e. the number of instances of residual pixel values, of all possible instances of residual pixel values. For the example above, the residual pixel

values can range from -255 to +255. While it is possible to construct local residual histograms with as many recording bins as there are possible instances of residual pixel values, in general it is not necessary. For most digital images, only a small percentage of residual pixel values exhibit values near the extremes of the possible range. The present invention uses 101 total recording bins for each local residual histogram. One of the recording bins corresponds to residual pixel values of 50 and greater. Similarly, one other recording bin corresponds to residual pixel values of -50 and lower. The other 99 recording bins each correspond to a single residual pixel value for the numerical range from -49 to +49.

Referring to FIG. 3, the noise table calculator 140 receives a set of local residual histograms and calculates the local noise characteristic table 105 in the form of a table of standard deviation values. For each of the local residual histograms relating to a particular color digital image channel and pixel value range, the noise table calculator 140 derives a noise standard deviation value from the value of the recording cells of the local residual histogram. The preferred embodiment of the present invention uses equation (2) to calculate the standard deviation value  $\sigma_n$

$$\sigma_n = \left( (1/N) \sum_k RC_v(k) (x - x_m)^2 \right)^{1/2} \quad (2)$$

where the variable  $x$  represents the average pixel value of the residual pixel values accumulated in the  $k^{\text{th}}$  recording cell as given by Table (1) and  $RC_v(k)$  represents the number of residual pixel values accumulated by the  $k^{\text{th}}$  recording cell.

$$x = V(k) \quad (3)$$

The variable  $x_m$  represents the arithmetic mean value of the corresponding residual pixel values given by equation (4),

$$x_m = (1/N) \sum_k x \quad (4)$$

and the variable  $N$  represents the total number of residual pixel values recorded by the updated residual histogram given by equation (5).

$$N = \sum_k RC_v(k) \quad (5)$$

An alternative embodiment of the present invention performs an alpha-trimmed standard deviation calculation. In this embodiment a first approximation to the standard deviation  $\sigma_e$  is calculated using the method described above. The calculation of  $\sigma_n$  is then calculated using the only recording  
 5 cells with corresponding residual pixel values that are within a limited range of zero. The formula for the standard deviation calculation  $\sigma_n$  is given by equation (6)

$$\sigma_n = \left( (1/N) \sum_k \gamma RC_v(k) (x - x_m)^2 \right)^{1/2} \quad (6)$$

where the variable  $\gamma$  is given by equation (7)

$$\gamma = 1 \quad \text{if } |x| < \alpha \sigma_e \quad (7)$$

$$\gamma = 0 \quad \text{if } |x| \geq \alpha \sigma_e$$

where the variable  $\alpha$  is set to 3.0. This alternative embodiment of the present invention is more computationally intensive than the preferred embodiment but does yield more accurate results via the rejection of out-lying residual pixel values  
 15 from adversely contributing to the calculation of the standard deviation  $\sigma_n$  value.

Table 2 below is an example of a noise characteristic table produced with the present invention.

Table 2

20

average pixel value	Standard deviation of red channel	Standard deviation of green channel	Standard deviation of blue channel
16	3.28	3.62	3.21
48	3.71	3.20	3.38
80	3.77	4.14	4.50
112	4.57	4.35	4.21
144	4.98	4.25	4.37
176	5.05	4.11	6.21
208	5.05	5.64	6.29
240	2.71	4.27	3.87

Those skilled in the art will recognize that the present invention can be practiced with calculated quantities other than the standard deviation that relate to the noise present in digital images. For example, the statistical variance (a squared function of the standard deviation) or statistical median can also be derived from the residual histograms and be used to form a table of noise characteristic values.

The present invention uses a set of residual histograms to record the calculated statistics. A set of histograms is an example of a statistical table from which a noise characteristic table can be derived. Thus, the set of local residual histograms constitutes a statistical table, i.e. a local statistical table. Those skilled in the art will recognize that the present invention can be practiced with other forms of statistical tables. For example, the residual digital images could be stored and serve as a statistical table. It should be noted that the present invention uses a set of residual histograms as the form for the statistical table due to its inherent computational and storage simplicity and economy.

The present invention produces more accurate noise characteristic tables through the feature of combining the residual statistics of multiple digital images. With more pixel data considered from multiple digital images, the standard deviation values of the calculated noise characteristic table converge to the true inherent noise characteristics of the underlying recording medium. For many digital imaging applications, a plurality of digital images derived from a common image source will be affected by a common noise source.

The above discussion has included details of practicing the present invention for digital images of general type. However, most digital imaging systems accept digital images from a variety of sources. For example, the image capture device 10a and 10b shown in FIG. 1 could be a photographic film scanner while the image capture device 10c could be a digital camera, digital camcorder, or print scanner. The image capture device can contribute noise to the digital images it produces. However, the inherent noise in the capture medium usually dominates the overall noise characteristics of the resultant digital images. For

example, while a photographic film scanner can produce digital images from any photographic film type, in general, some photographic films are inherently noisier than others. A photographic film sample is an example of a photographic image. Other examples of photographic images can include, but are not limited to, a CCD imaging electronic device and a photographic print.

In an alternative embodiment of the present invention, the image capture devices 10a, 10b, and 10c shown in FIG. 1 are capable of producing a source type identification tag 103, as shown in FIG. 2, which uniquely identifies a set of digital images as belonging to a particular group. In the example given above, a photographic film sample Kodak Generation 6 Gold 200 film is scanned by the image capture device 10a which produces a set of source digital images 101 and a source type identification tag 103. The digital imaging system maintains a plurality of stored source type identification tags which correspond to a plurality of stored default noise characteristic tables which correspond to different types of photographic films, print scanners, and digital cameras or the like. The digital imaging system uses the source type identification tag to select the appropriate default noise characteristic table. Referring to FIG. 3, the source type identification tag 103 is received by the digital image indexer 115 of the noise estimation module 110 shown in FIG. 2. The source type identification tag 103 identifies the source digital images 101 as being Kodak Generation 6 Gold 200 film. Digital images produced by other image capture devices, such as a particular model digital camera, have a corresponding unique source type identification tag. In similar fashion, the set of digital images marked with a source type identification tag are processed to produce a local noise characteristic table 105 which in turn is used to generate enhanced digital images 102. The source type identification tag 103 can also further identify a set of digital images that belong to a particular consumer. For this alternative embodiment, just the digital images marked with the particular consumer's source type identification tag 103 will be processed as a set. Of course, it is also possible that a particular consumer may issue more than one set of photographic images for processing.

The above described alternative embodiment of the present invention makes use of grouping digital images based on the source of the imagery. The statistical accuracy of the calculated noise characteristic table can be further improved if the statistics from previously processed sets of source digital images derived from the same source of imagery are combined. In a further alternative embodiment of the present invention a default statistical table 106 (as shown in FIG. 4), i.e. maintained and provided by the digital imaging system, is used in conjunction with the pixels from the source digital images 101 to calculate a local noise characteristic table 105 for the source digital images 101. However, the digital imaging system, shown in FIG. 1, stores a default statistical table 106 corresponding to each unique source type identification tag 103. Thus, the default statistical table 106 corresponding to Kodak Generation 6 Gold 200 film is used to process the source digital images 101 derived from the scanning the Kodak Generation 6 Gold 200 film sample with the image capture device 10a. It is important to note that if a different sample of Kodak Generation 6 Gold 200 film is scanned by the image capture device 10b, the same default statistical table corresponding to Kodak Generation 6 Gold 200 film is used. Thus, the default statistical table 106 is selected on the basis of the type of photographic film and not necessarily on the type of or individual unit image capture device. This feature of the present invention allows the default statistical table 106, and consequently the resultant calculated local noise characteristic table 105, to track or relate to the type of photographic film manufactured. Since the present invention automatically updates the default statistical table 106 and can derive the default statistical table 106 from the pixel values of digital images, the present invention can be used with new types of manufactured photographic film without the need of a disseminated a data base of either statistical tables or noise characteristic tables.

Those skilled in the art will recognized that this feature of the present invention can easily be extended to include other sources of digital images. For example, the image capture device 10c can be a digital still camera,



such as the Kodak DCS 290. For this example, the image capture device 10c produces a unique source type identification tag 103. In this manner any newly produced digital camera which produces a new and unique source type identification tag can be processed effectively with the present invention. When  
 5 the digital imaging systems shown in FIG. 1 encounters a previously unknown source type identification tag 103, a new default statistical table 106 is created.

In another alternative embodiment of the present invention, the digital imaging system shown in FIG. 1 maintains a separate database of default statistical tables 106, one for each source identification tag 103, for each image  
 10 capture device 10a and 10b. Since the image capture device can contribute some noise to the digital images it produces, maintaining separate databases of default statistical tables for each image capture device results in more accurate noise characteristic tables.

As shown in FIG. 4, the residual statistical accumulator 130  
 15 combines the default statistical table 106, in the form of a default residual histograms, with the local residual histograms. While the local residual histograms record residual pixel values as derived from the currently processed set of source digital images 101, the default residual histograms record the residual pixel values as derived from the previously processed digital images. Thus, the  
 20 default residual histograms have exactly the same form as the local residual histograms, i.e. one local residual histogram for each pixel value sub-range of each color digital image channel.

The present invention uses more than one method of combining the local residual histograms with the default residual histograms, however, each  
 25 method combines a single local residual histogram with the corresponding default residual histogram. Therefore, it is appropriate only to discuss the method with respect to the combination of two histograms with the assumption that each combining method is repeated for all the pairs of histograms.

This alternative embodiment of the present invention uses a direct  
 30 method of combining the data contained in the local residual histogram and

default residual histogram. That is, the numbers contained in each recording cell of the local residual histogram are added directly to the corresponding recording cell of the default residual histogram. Thus, after the combining step has been performed, the updated values of each recording cell is given by the sum of the  
 5 previous value of the recording cell with the value contained in the corresponding recording cell of the local residual histogram.

Since the recording cells of the default residual histogram contains the sum total of residual pixel values derived from the set of source digital images as well as previous processed digital images, the numerical range of the computer  
 10 implementation can be exceeded. To avoid a numerical overflow condition, the default residual histogram can be re-normalized. The process of re-normalization includes scanning the values of the recording cells to determine the maximum value, comparing this maximum value to a predetermined allowable value. If the maximum value is greater than the a predetermined allowable value, the values of  
 15 all the recording cells are divided by a constant numerical factor. This process of re-normalization of the default residual histogram can be performed either before or after the process of combining the local residual histogram with the default residual histogram. The preferred embodiment of the present invention performs the re-normalization process before the combining process.

20 An alternative embodiment of the present invention produces the updated residual histogram by calculating a weighted average between the default residual histogram and the local residual histogram. For each recording cell of the default residual histogram  $RC_d$  and its corresponding recording cell of the local residual histogram  $RC_l$ , the updated recording cell value  $RC_v$  is calculated using  
 25 the formula:

$$RC_v = \beta RC_d + (1 - \beta) RC_l \quad (8)$$

where the variable  $\beta$  is a numerical weighting factor. The present invention uses  $\beta$  value of 0.99 for a which heavily weights the contribution of the default residual histogram. This alternative embodiment of the present invention uses a linear  
 30 combination of the local residual histogram and the default residual histogram.

The present invention can be practiced by recording a default noise characteristic table, i.e. maintained and provided by the digital imaging system, instead of recording the residual histograms. FIG. 5 shows the details of an alternative embodiment of the noise estimation module 110. As described in the alternative embodiment above, a set of local residual histograms is calculated from the source digital images 101. The noise table calculator 140 receives the local residual histograms and produces a local noise characteristic table 105. The noise table generator 150 receives the local noise characteristic table and a default noise characteristic table 107 and produces an updated noise characteristic table 108.

This updated noise characteristic table 108 replaces the default noise characteristic table 107 for the next source digital image 101 to be processed. The local noise characteristic table 105 and default noise characteristic table 107 are combined by calculating a linear combination of these two tables element for element. Good values for the linear combination coefficients are 0.99 contribution for the default noise characteristic table values and 0.01 for the local noise characteristic table values. Although this alternative embodiment of the present invention can be used to generate robust noise characteristic tables, the alternative embodiment that combines residual histograms generally produces more accurate results.

The calculated noise characteristic table is used in conjunction with spatial filters to produce an enhanced digital image 102 from a source digital image 101. A spatial filter is any method which uses pixel values sampled from a local region about a pixel of interest to calculate an enhanced pixel value which replaces the pixel of interest. Those spatial filters which reduce spatial modulation, for at least some pixels in an effort to remove noise from the processed digital image, can be considered noise reduction filters. Those spatial filters which increase spatial modulation, for at least some pixels, in an effort to enhance spatial detail noise in the processed digital image, can be considered spatial sharpening filters. It should be noted that it is possible for a single spatial filter to be considered both a noise reduction filter as well as a spatial sharpening filter. The present invention can be used with any digital image processing

method which makes uses of a noise characteristic table to produce an enhanced digital image 102. Spatial filters that adjust a processing control parameter as a function of either the color or numerical value of pixels are adaptive spatial filters. The present invention uses a noise reduction filter and a spatial sharpening filter which are responsive to a noise characteristic table.

Referring to FIG. 2, the preferred embodiment of the present invention employs a noise reduction module 22 as part of the image processing method to produce enhanced digital images 102. As such, the source digital image 101 and the local noise characteristic table 105 are received by the noise reduction module 22 which produces on output a noise reduced digital image.

It is important to note that for many practical digital imaging image systems, other image processing processors need to be included. As long as these other image processing processors accept a digital image as input and produce a digital image on output, more of these type of image processing modules can be inserted in the image processing chain in between a noise reduction module 22 and a spatial sharpening module 23.

The present invention uses a modified implementation of the Sigma filter, described by Jong-Sen Lee in the journal article *Digital Image Smoothing and the Sigma Filter*, Computer Vision, Graphics, and Image Processing Vol 24, p. 255-269, 1983, as a noise reduction filter to enhance the appearance of the processed digital image. The values of the pixels contained in a sampled local region,  $n$  by  $n$  pixels where  $n$  denotes the length of pixels in either the row or column direction, are compared with the value of the center pixel, or pixel of interest. Each pixel in the sampled local region is given a weighting factor of one or zero based on the absolute difference between the value of the pixel of interest and the local region pixel value. If the absolute value of the pixel value difference is less or equal to a threshold  $\epsilon$ , the weighting factor is set to one. Otherwise, the weighting factor is set to zero. The numerical constant  $\epsilon$  is set to two times the expected noise standard deviation. Mathematically the expression for the calculation of the noise reduced pixel value is given as

$$q_{mn} = \sum_{ij} a_{ij} p_{ij} / \sum_{ij} a_{ij} \quad (9)$$

and

$$a_{ij} = 1 \quad \text{if } |p_{ij} - p_{mn}| \leq \varepsilon$$

$$a_{ij} = 0 \quad \text{if } |p_{ij} - p_{mn}| > \varepsilon$$

5 where  $p_{ij}$  represents the  $ij^{\text{th}}$  pixel contained in the sampled local region,  $p_{mn}$  represents the value of the pixel of interest located at row  $m$  and column  $n$ ,  $a_{ij}$  represents a weighting factor, and  $q_{mn}$  represents the noise reduced pixel value. Typically, a rectangular sampling region centered about the center pixel is used with the indices  $i$  and  $j$  varied to sample the local pixel values.

10 The signal dependent noise feature is incorporated into the expression for  $\varepsilon$  given by equation (10)

$$\varepsilon = Sfac \sigma_n(p_{mn}) \quad (10)$$

where  $\sigma_n$  represents the noise standard deviation of the source digital image 101 evaluated at the center pixel value  $p_{mn}$  as described by equations (3) and (8) above.

15 The parameter *Sfac* is termed a scale factor can be used to vary the degree of noise reduction. The optimal value for the *Sfac* parameter has been found to be 1.5 through experimentation however values ranging from 1.0 to 3.0 can also produce acceptable results. The calculation of the noise reduced pixel value  $q_{mn}$  as the division of the two sums is then calculated. The process is completed for some or

20 all of the pixels contained in the digital image channel and for some or all the digital image channels contained in the digital image. The noise reduced pixel values constitute the noise reduced digital image. The modified implementation of the Sigma filter is an example of a noise reduction filter that uses a noise characteristic table and is therefore an adaptive noise reduction filter which varies

25 the amount of noise removed as a function of the pixel color and numerical value.

Referring to FIG. 2, the preferred embodiment of the present invention employs a spatial sharpening module 23 as part of the image processing method to produce an enhanced digital image 102. As such, the noise reduced

digital image and the local noise characteristic table 105 are received by the spatial sharpening module 23 which produces on output an enhanced digital image 105.

Although the present invention can be used with any spatial sharpening filter which utilizes a priori knowledge of the noise characteristics, the preferred embodiment uses a modified implementation of the method described by Kwon et al. in U.S. Patent 5,081,692. This spatial sharpening method performs an unsharp masking operation by filtering the input digital image with a spatial averaging 2-dimensional Gaussian filter (characterized by a standard deviation of 2.0 pixels) which results in a blurred digital image. The blurred digital image is subtracted from the input digital image to form a high-pass residual. In the method disclosed by Kwon et al. a local variance about a pixel of interest is calculated by using the pixel data from the high-pass residual. Based on the value of the local variance a sharpening factor is adjusted so as to amplify large signals more than small amplitude signals. The amplification factor  $\phi$  is therefore a factor of the local variance  $v$ , i.e.  $\phi(v)$ .

The present invention modifies the method taught by Kwon et al. to make the amplification factor  $\phi(v)$  a function of the estimated noise, i.e.  $\phi(v, \sigma_n)$ . The amplification function  $f$  is given by a gamma function, or integral of a Gaussian probability function, as given by equation (11).

$$\phi(v) = \frac{y_o + y_{\max} \sum e^{-(v - v_o)^2/2s^2}}{y_o + y_{\max} \sum e^{-(v_{\max} - v_o)^2/2s^2}} \quad (11)$$

where  $y_o$  represents a minimum amplification factor  $y_{\max}$  represents a maximum amplification factor,  $v_{\max}$  represents a maximum abscissa value of the variable  $v$ ,  $v_o$  represents a transition parameter and  $s$  represents a transition rate parameter.

The variable  $v_o$  is a function of the noise standard deviation value  $\sigma_n$  as per equation (12)

$$v_o = Sfac2 \sigma_n (p_{nm}) \quad (12)$$

where the scaling factor  $Sfac_2$  determines the sensitivity of the sharpening sensitivity to the noise and the noise standard deviation value  $\sigma_n$  is as described above in equations (3) and (8). The optimal values for the variables used in equation (12) depend on the digital imaging application. The present invention  
 5 uses a value of 1.0 for  $y_0$  which results in no spatial sharpening for noisy regions. A value of 3.0 is used for  $y_{max}$ , however, this variable is sensitive to user preference with values ranging from 2.0 to 4.0 producing acceptable results. The value of  $Sfac_2$  should be set to between 1.0 and 2.0 with 1.5 as optimal. The variables should be set to values in the range from  $v_0 / 2$  to  $v_0 / 10$  for reasonable  
 10 results. The variable  $v_{max}$  should be set to a value much larger than the expected noise, e.g. 20 times the value of  $\sigma_n$ .

While the preferred embodiment of the present invention calculates a noise characteristic table and then subsequently uses the noise characteristic table to produce an enhanced digital image, some digital imaging systems may be  
 15 configured to separate the calculation phase from the enhancement phase. In an alternative embodiment of the present invention, the calculated noise characteristic table is stored with the source digital image 101 as meta-data, i.e. non-pixel information. The source digital image 101 with meta-data can be transmitted to a remote site or stored for safe keeping to be used at a later time or another site.  
 20 Any of the above mentioned noise characteristic tables can be stored as meta-data. In general a noise characteristic table requires much less memory storage than a set of residual histograms. However, a set of residual histograms can be stored with the source digital image 101 as meta-data.

A computer program product may include one or more storage  
 25 medium, for example; magnetic storage media such as magnetic disk (such as a floppy disk) or magnetic tape; optical storage media such as optical disk, optical tape, or machine readable bar code; solid-state electronic storage devices such as random access memory (RAM), or read-only memory (ROM); or any other physical device or media employed to store a computer program having  
 30 instructions for operating one or more computers to practice a method according

to the present invention.

The invention has been described in detail with particular reference to certain preferred embodiments thereof, but it will be understood that variations and modifications can be effected within the spirit and scope of the invention.

100 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117 118 119 120 121 122 123 124 125 126 127 128 129 130 131 132 133 134 135 136 137 138 139 140 141 142 143 144 145 146 147 148 149 150 151 152 153 154 155 156 157 158 159 160 161 162 163 164 165 166 167 168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199 200 201 202 203 204 205 206 207 208 209 210 211 212 213 214 215 216 217 218 219 220 221 222 223 224 225 226 227 228 229 230 231 232 233 234 235 236 237 238 239 240 241 242 243 244 245 246 247 248 249 250 251 252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271 272 273 274 275 276 277 278 279 280 281 282 283 284 285 286 287 288 289 290 291 292 293 294 295 296 297 298 299 300 301 302 303 304 305 306 307 308 309 310 311 312 313 314 315 316 317 318 319 320 321 322 323 324 325 326 327 328 329 330 331 332 333 334 335 336 337 338 339 340 341 342 343 344 345 346 347 348 349 350 351 352 353 354 355 356 357 358 359 360 361 362 363 364 365 366 367 368 369 370 371 372 373 374 375 376 377 378 379 380 381 382 383 384 385 386 387 388 389 390 391 392 393 394 395 396 397 398 399 400 401 402 403 404 405 406 407 408 409 410 411 412 413 414 415 416 417 418 419 420 421 422 423 424 425 426 427 428 429 430 431 432 433 434 435 436 437 438 439 440 441 442 443 444 445 446 447 448 449 450 451 452 453 454 455 456 457 458 459 460 461 462 463 464 465 466 467 468 469 470 471 472 473 474 475 476 477 478 479 480 481 482 483 484 485 486 487 488 489 490 491 492 493 494 495 496 497 498 499 500 501 502 503 504 505 506 507 508 509 510 511 512 513 514 515 516 517 518 519 520 521 522 523 524 525 526 527 528 529 530 531 532 533 534 535 536 537 538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 582 583 584 585 586 587 588 589 590 591 592 593 594 595 596 597 598 599 600 601 602 603 604 605 606 607 608 609 610 611 612 613 614 615 616 617 618 619 620 621 622 623 624 625 626 627 628 629 630 631 632 633 634 635 636 637 638 639 640 641 642 643 644 645 646 647 648 649 650 651 652 653 654 655 656 657 658 659 660 661 662 663 664 665 666 667 668 669 670 671 672 673 674 675 676 677 678 679 680 681 682 683 684 685 686 687 688 689 690 691 692 693 694 695 696 697 698 699 700 701 702 703 704 705 706 707 708 709 710 711 712 713 714 715 716 717 718 719 720 721 722 723 724 725 726 727 728 729 730 731 732 733 734 735 736 737 738 739 740 741 742 743 744 745 746 747 748 749 750 751 752 753 754 755 756 757 758 759 760 761 762 763 764 765 766 767 768 769 770 771 772 773 774 775 776 777 778 779 780 781 782 783 784 785 786 787 788 789 790 791 792 793 794 795 796 797 798 799 800 801 802 803 804 805 806 807 808 809 810 811 812 813 814 815 816 817 818 819 820 821 822 823 824 825 826 827 828 829 830 831 832 833 834 835 836 837 838 839 840 841 842 843 844 845 846 847 848 849 850 851 852 853 854 855 856 857 858 859 860 861 862 863 864 865 866 867 868 869 870 871 872 873 874 875 876 877 878 879 880 881 882 883 884 885 886 887 888 889 890 891 892 893 894 895 896 897 898 899 900 901 902 903 904 905 906 907 908 909 910 911 912 913 914 915 916 917 918 919 920 921 922 923 924 925 926 927 928 929 930 931 932 933 934 935 936 937 938 939 940 941 942 943 944 945 946 947 948 949 950 951 952 953 954 955 956 957 958 959 960 961 962 963 964 965 966 967 968 969 970 971 972 973 974 975 976 977 978 979 980 981 982 983 984 985 986 987 988 989 990 991 992 993 994 995 996 997 998 999 1000



**PARTS LIST**

10	image capture device
10a	image capture device
10b	image capture device
10c	image capture device
20	digital image processor
22	noise reduction module
23	spatial sharpening module
30	image output device
30a	image output device
30b	image output device
40	general control computer
50	monitor device
60	input control device
70	offline memory device
101	source digital image
102	enhanced digital image
103	source type identification tag
105	local noise characteristic table
106	default statistical table
107	default noise characteristic table
108	updated noise characteristic table
110	noise estimation module
115	digital image indexer
120	residual transform module
130	residual statistic accumulator
140	noise table calculator